

# Synthesised sinewave generator + tachometer for turntable motors

v1.0     Richard Balmford

This project consists of a PCB and Arduino firmware to generate 2 or 3 phases of sinewaves suitable for driving turntable motors, along with a tachometer function to display the turntable speed. The PCB mounts directly on the Arduino Uno, with one required for 2 phases, and 2 for 3 phases.

The sinewave outputs are a nominal 1.3v peak-peak and will require amplification to the voltage required by the motor.

The tachometer requires any sensor that generates 5v pulses.

## Features

- 31.4kHz PWM synthesis + 2-stage low-pass filter
- suitable for 50Hz or 60Hz motors (selectable in firmware)
- generates 2 (0° and 90 °) or 3 (0 °, 120 ° and 240 °) phases of sinewave
- electronic speed switching for 33/45rpm
- tuneable frequency and relative phase, stored in non-volatile memory
- buttons, and Bluetooth + RemoteXY App interfaces
- integrated tachometer, displayed via Bluetooth interface
- tachometer has selectable pulses-per-rev and averaging (in firmware)
- selectable start ON or OFF (in firmware)



# BOM

| Designation    | Part   | Quantity, 2-phase | Quantity, 3 phase |
|----------------|--|-------------------|-------------------|
|                | Arduino UNO                                    | 1                 | 1                 |
| P1             | PCB  | 1                 | 2                 |
| U1             | OPA2134  | 1                 | 2                 |
|                | DIL socket, 8-pin                              | 1 *               | 2 *               |
| R1, R2, R12    | 10k $\Omega$                                   | 3                 | 5                 |
| R3, R4         | 12k $\Omega$                                   | 2                 | 3                 |
| R5, R6         | 3.3k $\Omega$                                  | 2                 | 3                 |
| R7, R8         | 1k $\Omega$                                    | 2                 | 3                 |
| R9, R10        | 220k $\Omega$                                  | 2                 | 3                 |
| R11            | 4.7k $\Omega$                                  | 1                 | 1                 |
| R13            | 470 $\Omega$ (1)                               | 1                 | 1                 |
| C1             | 10 $\mu$ F, electrolytic, 6.3v+, 0.1" spacing  | 1                 | 2                 |
| C2, C3, C7, C8 | 100nF, 0.2" spacing                            | 4                 | 6                 |
| C4, C5         | 4.7 $\mu$ F, electrolytic, 6.3v+, 0.1" spacing | 2                 | 3                 |
| C6             | 0.1 $\mu$ F, decoupling, 0.2" spacing          | 1                 | 2                 |
| KEY1           | miniature momentary push switch                | 1                 | 1                 |
| J7             | miniature SPDT slide switch                    | 1                 | 1                 |
| LED            | LED  | 1 *               | 1 *               |
| H2             | 4-pin header, female                           | 1 (2)             | -                 |
|                | 0.1" header strip, male (3)                    |                   |                   |
|                | 0.1" stacking headers, 6 + 8 + 8 + 10 pins     | -                 | 1                 |
|                | screw terminal, 5mm, 4 way                     | 1 *               | 1 *               |
|                | screw terminal, 5mm, 2 way                     | -                 | 1 *               |

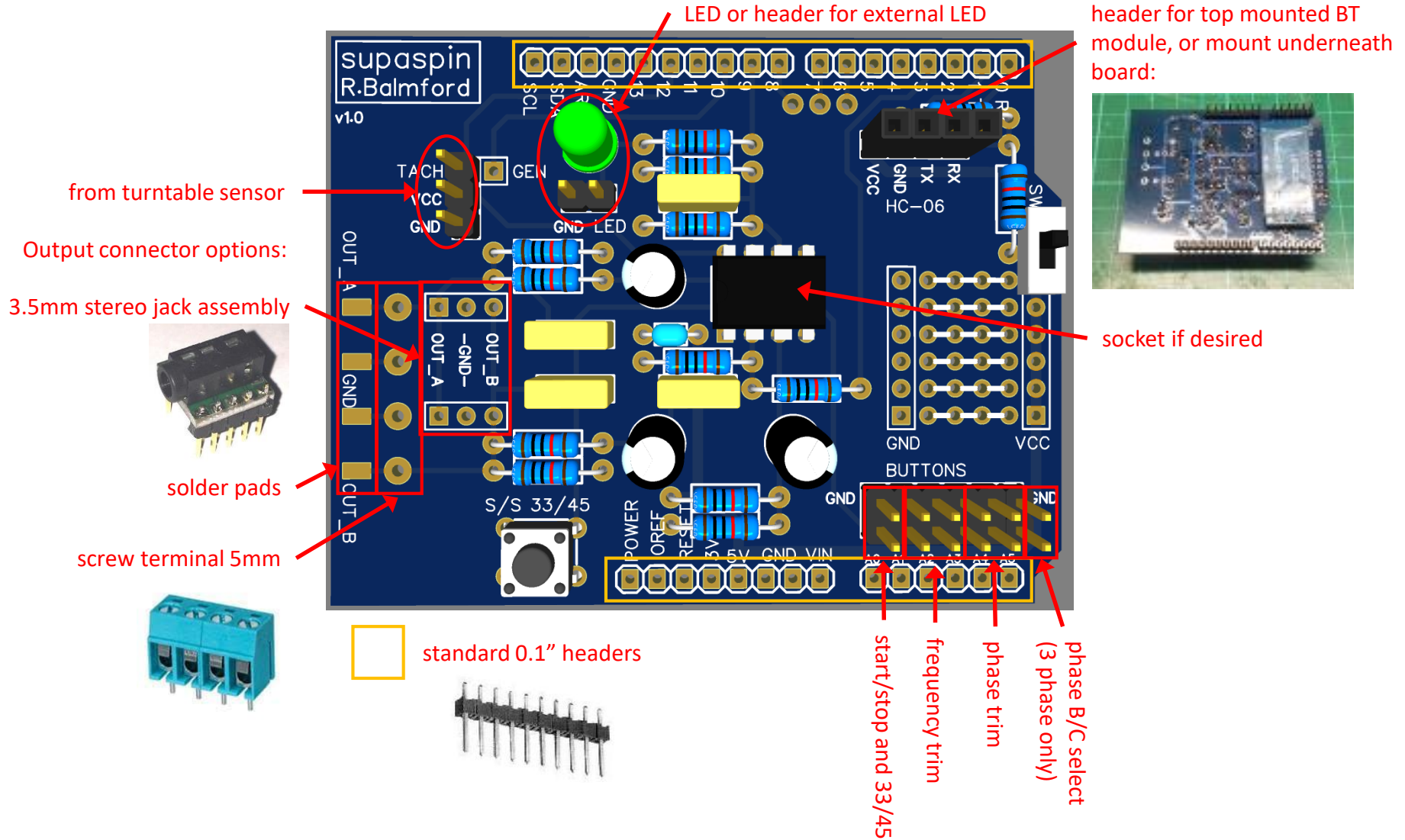
\* optional

(1) choose for desired LED brightness

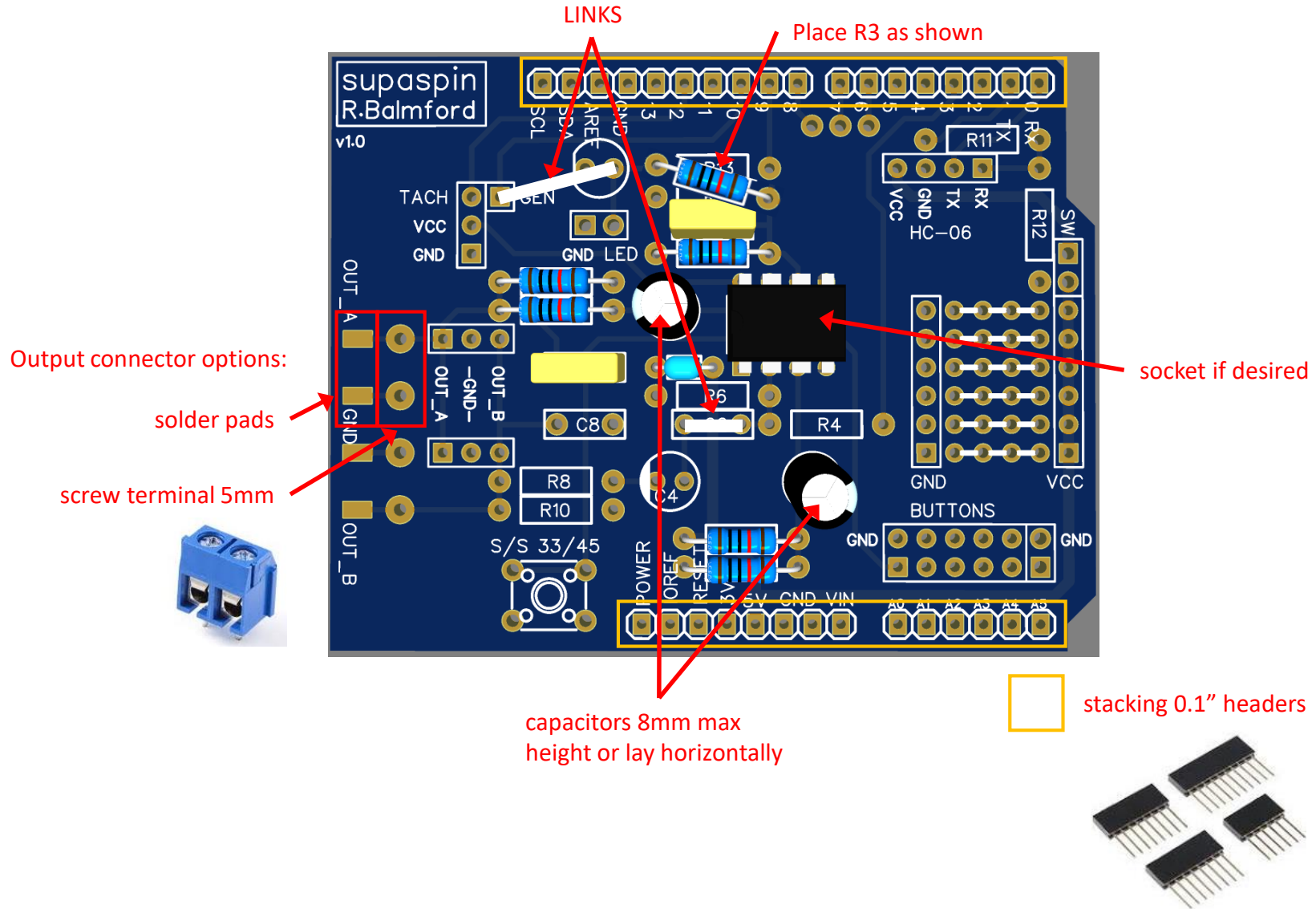
(2) for removable mounting of BT module on top of board; alternatively mount permanently underneath

(3) sufficient for PCB-Arduino, tachometer + button headers

- 2 phase board (all builds)



- 3rd phase board (3 phase builds only)



## Firmware

You will need to upload the firmware to the Arduino board, using the standard Arduino IDE. Before doing so, there are some setup choices to be made at the top of the file.

BT\_SPEED:                      must match the serial BAUD rate of the HC-06 Bluetooth module

For sinewave synthesiser:

NR\_PHASES:                    2 or 3; choose according to your application

INIT\_RUN\_STATE:               choose whether to power up in ON state (1) or OFF state (0)

For tachometer:

CP\_REV:                        number of pulses per revolution

NR\_AVG:                        number of measurement of which to average (1 = no averaging, 2+ = averaging)

You will also need to load your board with the nominal defaults for the frequencies according to whether yours is a 50Hz or 60Hz motor. On first uploading, uncomment the corresponding line from:

```
#define SET_EE_50              for 50Hz motors
```

```
#define SET_EE_60              for 60Hz motors
```

Once uploaded, comment out the line and upload again. The defaults are now set, and any future tuning of the frequency or phase parameters will be stored.

# Interface

The Bluetooth + RemoteXY App interface can work alongside the button interface

